

Figure 6.30. Implementation of the FSM of Figure 6.3 in a CPLD.

```

module control (Clock, Resetn, w, R1in, R1out, R2in, R2out, R3in, R3out,Done);
    input Clock, Resetn, w;
    output R1in, R1out, R2in, R2out, R3in, R3out, Done;
    reg [2:1] y, Y;
    parameter [2:1] A = 2'b00, B = 2'b01, C = 2'b10, D = 2'b11;

    // Define the next state combinational circuit
    always @(w, y)
        case (y)
            A: if (w) Y = B;
                else Y = A;
            B: Y = C;
            C: Y = D;
            D: Y = A;
        endcase

    // Define the sequential block
    always @(negedge Resetn, posedge Clock)
        if (Resetn == 0)    y <= A;
        else   y <= Y;

    // Define outputs
    assign R2out = (y == B);
    assign R3in = (y == B);
    assign R1out = (y == C);
    assign R2in = (y == C);
    assign R3out = (y == D);
    assign R1in = (y == D);
    assign Done = (y == D);

endmodule

```

Figure 6.35. Verilog code for the FSM in Figure 6.11.

```

module mealy (Clock, Resetn, w, z);
    input Clock, Resetn, w;
    output reg z;
    reg y, Y;
    parameter A = 1'b0, B = 1'b1;

    // Define the next state and output combinational circuits
    always @(w, y)
        case (y)
            A:   if (w)
                begin
                    z = 0;
                    Y = B;
                end
                else
                begin
                    z = 0;
                    Y = A;
                end
            B:   if (w)
                begin
                    z = 1;
                    Y = B;
                end
                else
                begin
                    z = 0;
                    Y = A;
                end
        endcase

    // Define the sequential block
    always @(negedge Resetn, posedge Clock)
        if (Resetn == 0) y <= A;
        else y <= Y;

endmodule

```

Figure 6.36. Verilog code for the Mealy machine of Figure 6.23.

```

module serial_adder (A, B, Reset, Clock, Sum);
    input [7:0] A, B;
    input Reset, Clock;
    output wire [7:0] Sum;
    reg [3:0] Count;
    reg s, y, Y;
    wire [7:0] QA, QB;
    wire Run;
    parameter G = 1'b0, H = 1'b1;

    shiftrne shift_A (A, Reset, 1'b1, 1'b0, Clock, QA);
    shiftrne shift_B (B, Reset, 1'b1, 1'b0, Clock, QB);
    shiftrne shift_Sum (8'b0, Reset, Run, s, Clock, Sum);

    // Adder FSM
    // Output and next state combinational circuit
    always @(QA, QB, y)
        case (y)
            G: begin
                s = QA[0] ^ QB[0];
                if (QA[0] & QB[0])  Y = H;
                else    Y = G;
                end
            H: begin
                s = QA[0] ~^ QB[0];
                if (~QA[0] & ~QB[0])  Y = G;
                else    Y = H;
                end
            default: Y = G;
        endcase

    // Sequential block
    always @(posedge Clock)
        if (Reset)  y <= G;
        else        y <= Y;

    // Control the shifting process
    always @(posedge Clock)
        if (Reset)      Count = 8;
        else if (Run)   Count = Count - 1;
        assign Run = |Count;

endmodule

```

Figure 6.49. Verilog code for the serial adder.

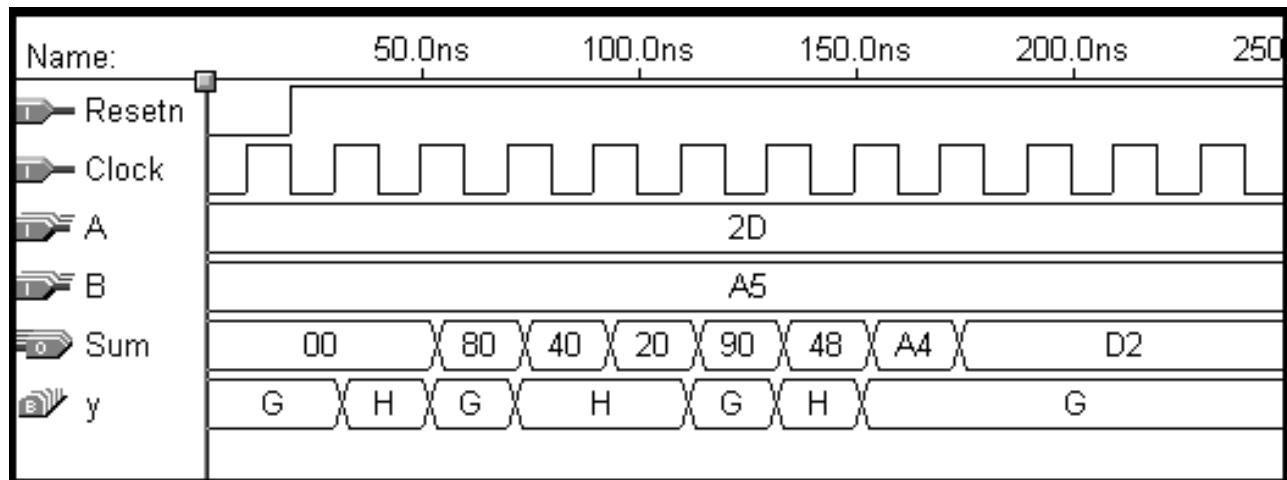
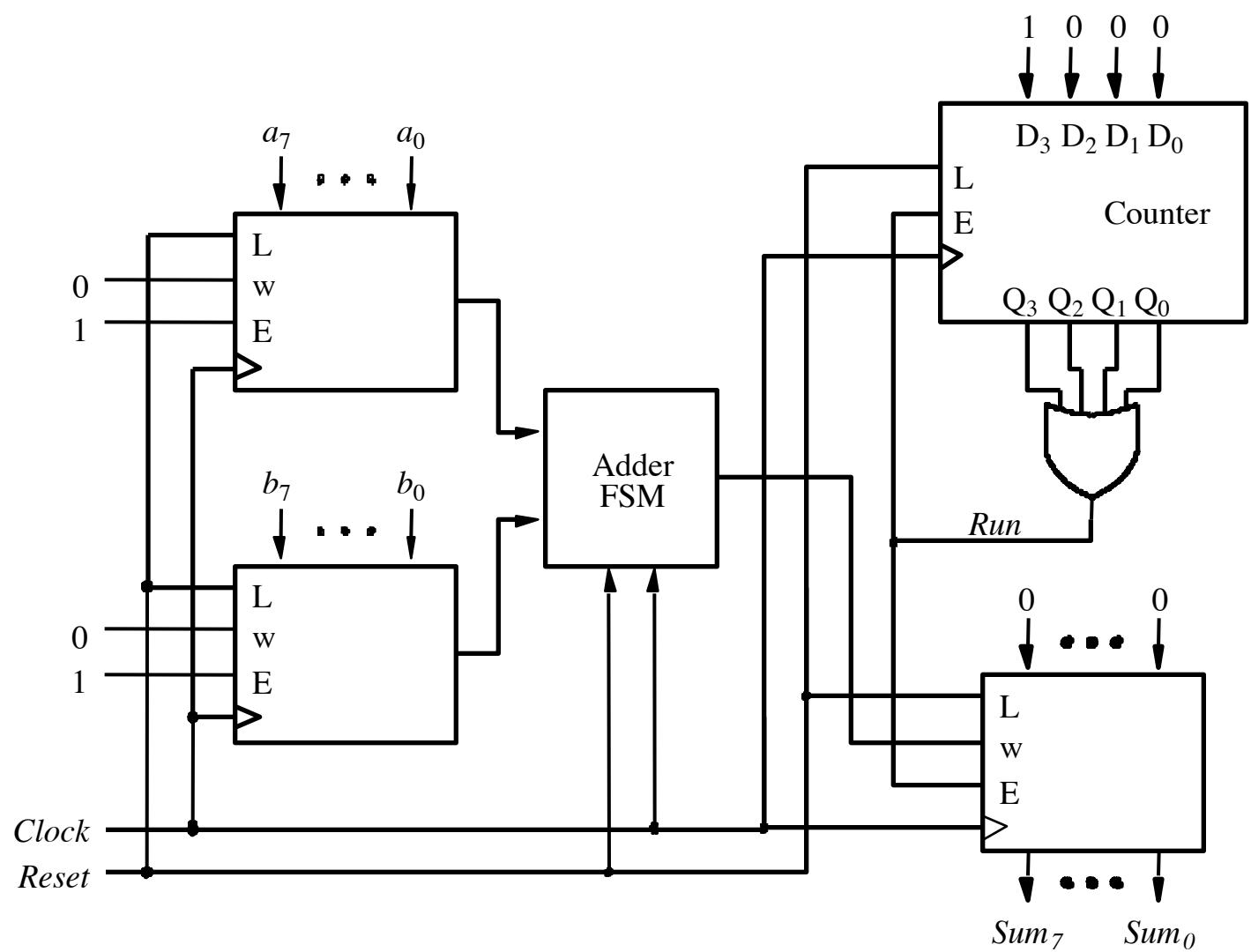


Figure 6.50. Synthesized serial adder.

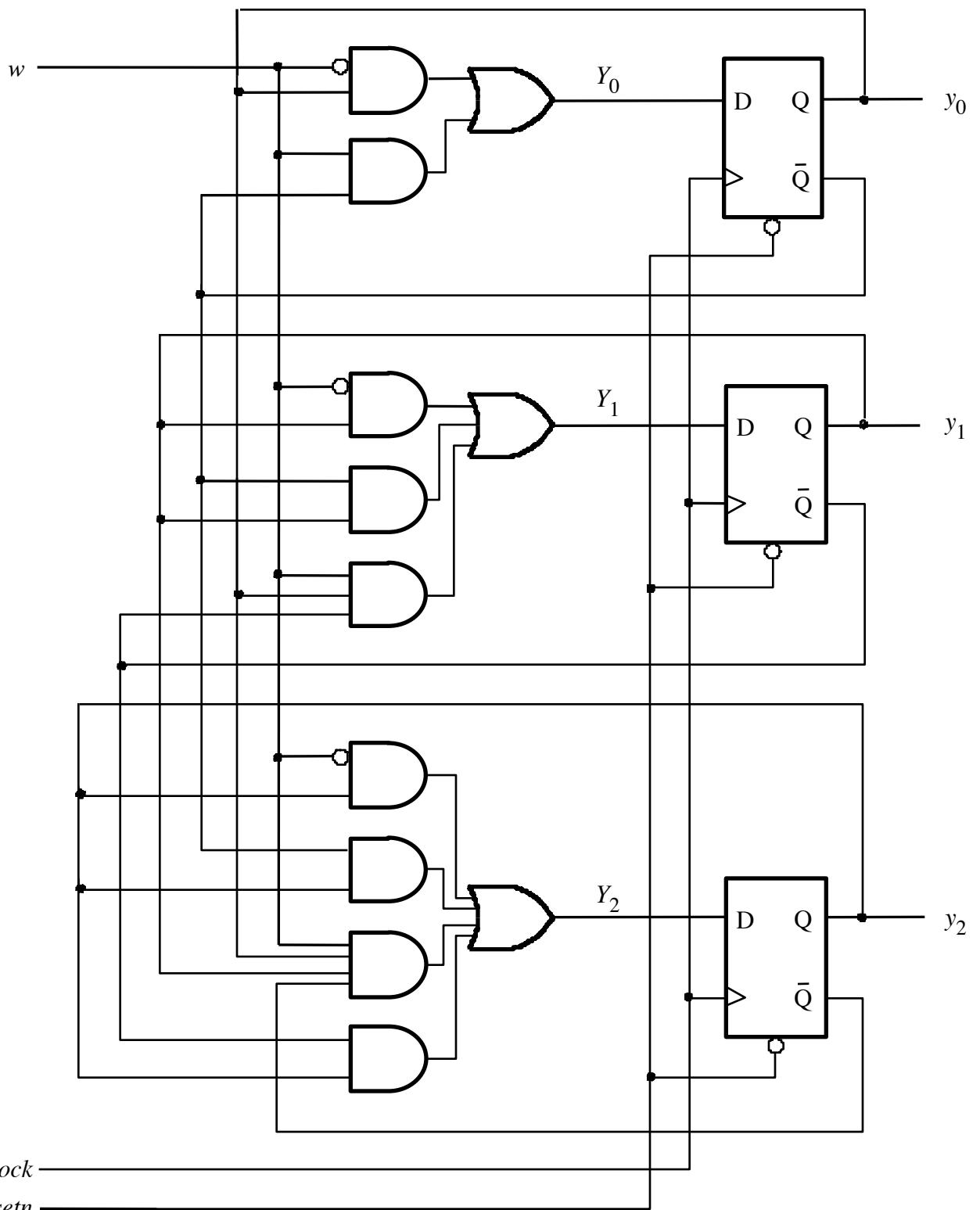


Figure 6.64. Circuit diagram for the counter implemented with D flip-flops.

$y_1y_0$	00	01	11	10
$wy_2$	0	d	d	0
00	0	d	d	0
01	0	d	d	0
11	1	d	d	1
10	1	d	d	1

$$J_0 = w$$

$y_1y_0$	00	01	11	10
$wy_2$	d	0	0	d
00	d	0	0	d
01	d	0	0	d
11	d	1	1	d
10	d	1	1	d

$$K_0 = w$$

$y_1y_0$	00	01	11	10
$wy_2$	0	0	d	d
00	0	0	d	d
01	0	0	d	d
11	0	1	d	d
10	0	1	d	d

$$J_1 = wy_0$$

$y_1y_0$	00	01	11	10
$wy_2$	d	d	0	0
00	d	d	0	0
01	d	d	0	0
11	d	d	1	0
10	d	d	1	0

$$K_1 = wy_0$$

$y_1y_0$	00	01	11	10
$wy_2$	0	0	0	0
00	0	0	0	0
01	d	d	d	d
11	d	d	d	d
10	0	0	1	0

$$J_2 = wy_0y_1$$

$y_1y_0$	00	01	11	10
$wy_2$	d	d	d	d
00	d	d	d	d
01	0	0	0	0
11	0	0	1	0
10	d	d	d	d

$$K_2 = wy_0y_1$$

Figure 6.66. Karnaugh maps for JK flip-flops in the counter.

```

module arbiter (r, Resetn, Clock, g);
    input [1:3] r;
    input Resetn, Clock;
    output wire [1:3] g;
    reg [2:1] y, Y;
    parameter Idle = 2'b00, gnt1 = 2'b01, gnt2 = 2'b10, gnt3 = 2'b11;

    // Next state combinational circuit
    always @(r, y)
        case (y)
            Idle: casex (r)
                3'b000: Y = Idle;
                3'b1xx: Y = gnt1;
                3'b01x: Y = gnt2;
                3'b001: Y = gnt3;
                default: Y = Idle;
            endcase
            gnt1: if (r[1]) Y = gnt1;
                  else Y = Idle;
            gnt2: if (r[2]) Y = gnt2;
                  else Y = Idle;
            gnt3: if (r[3]) Y = gnt3;
                  else Y = Idle;
            default: Y = Idle;
        endcase

    // Sequential block
    always @(posedge Clock)
        if (Resetn == 0) y <= Idle;
        else y <= Y;

    // Define output
    assign g[1] = (y == gnt1);
    assign g[2] = (y == gnt2);
    assign g[3] = (y == gnt3);

endmodule

```

Figure 6.74. Verilog code for the arbiter.

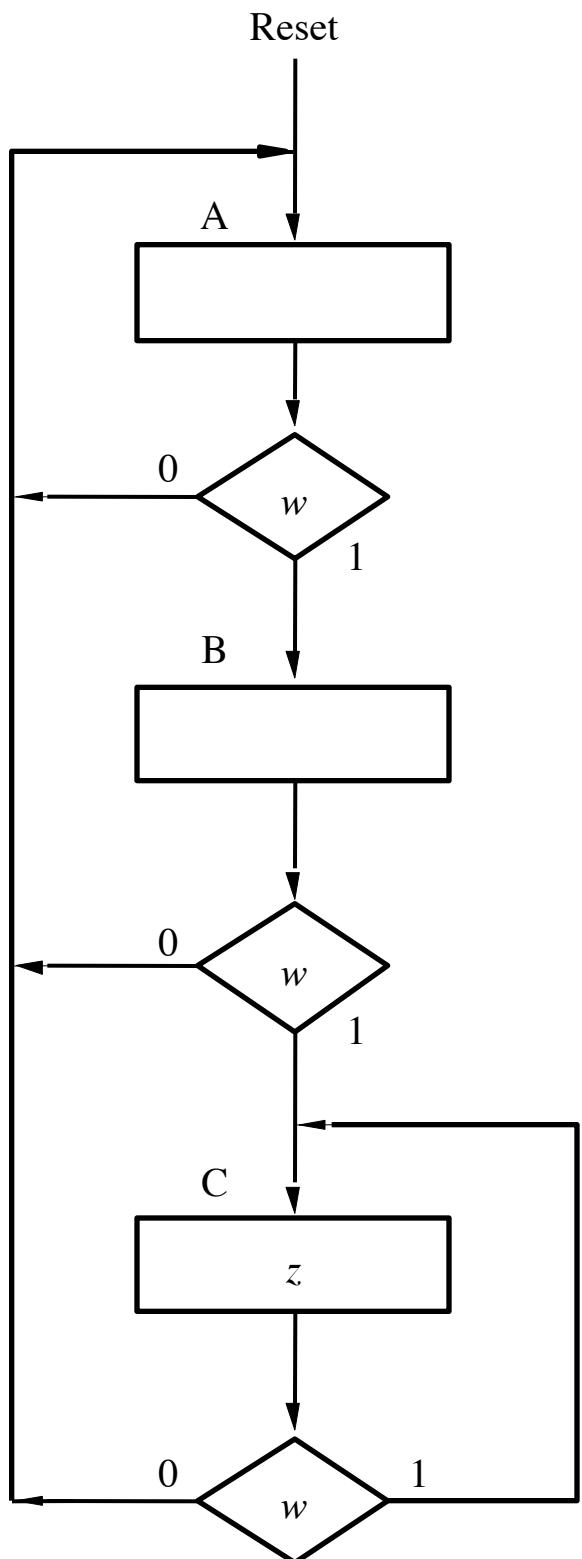


Figure 6.82. ASM chart for the FSM in Figure 6.3.

```
module sequence (Clock, Resetn, w, z);
    input Clock, Resetn, w;
    output z;
    reg [3:1] y, Y;
    parameter [3:1] A = 3'b000, B = 3'b001, C = 3'b010,
                  D = 3'b011, E = 3'b100;
```

```
// Define the next state combinational circuit
```

```
always @ (w, y)
```

```
case (y)
```

```
    A: if (w)    Y = D;
```

```
        else      Y = B;
```

```
    B: if (w)    Y = D;
```

```
        else      Y = C;
```

```
    C: if (w)    Y = D;
```

```
        else      Y = C;
```

```
    D: if (w)    Y = E;
```

```
        else      Y = B;
```

```
    E: if (w)    Y = E;
```

```
        else      Y = B;
```

```
    default:     Y = 3'bxxx;
```

```
endcase
```

```
// Define the sequential block
```

```
always @ (negedge Resetn, posedge Clock)
```

```
if (Resetn == 0) y <= A;
```

```
else y <= Y;
```

```
// Define output
```

```
assign z = (y == C) | (y == E);
```

```
endmodule
```

Figure 6.95. Verilog code for the FSM in Figure 6.86.

```

module seqmealy (Clock, Resetn, w, z);
    input Clock, Resetn, w;
    output reg z;
    reg [2:1] y, Y;
    parameter [2:1] A = 2'b00, B = 2'b01, C = 2'b11;
    // Define the next state and output combinational circuits
    always @(w, y)
        case (y)
            A: if (w) begin
                z = 0; Y = C;
            end
            else begin
                z = 0; Y = B;
            end
            B: if (w) begin
                z = 0; Y = C;
            end
            else begin
                z = 1; Y = B;
            end
            C: if (w) begin
                z = 1; Y = C;
            end
            else begin
                z = 0; Y = B;
            end
            default: begin
                z = 0; Y = 2'bxx;
            end
        endcase
    // Define the sequential block
    always @(negedge Resetn, posedge Clock)
        if (Resetn == 0) y <= A;
        else y <= Y;
endmodule

```

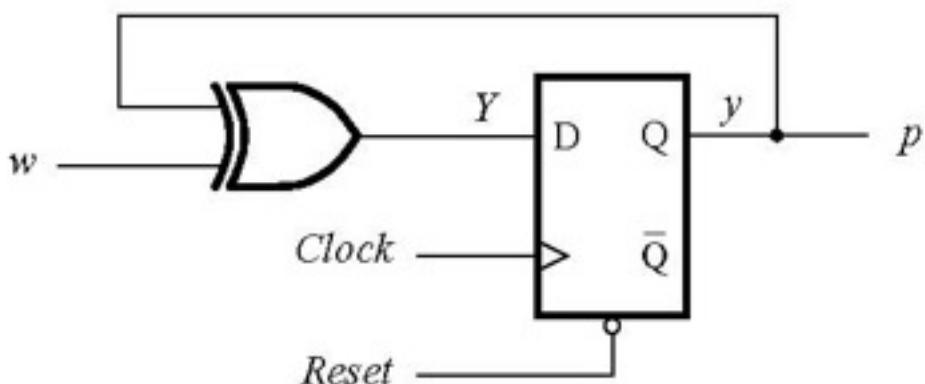
Figure 6.96. Verilog code for the FSM in Figure 6.91.

Present state	Next state		Output $p$
	$w = 0$	$w = 1$	
$S_{\text{even}}$	$S_{\text{even}}$	$S_{\text{odd}}$	0
$S_{\text{odd}}$	$S_{\text{odd}}$	$S_{\text{even}}$	1

(a) State table

Present state	Next state		Output $p$
	$w = 0$	$w = 1$	
	$y$	$Y$	
0	0	1	0
1	1	0	1

(b) State-assigned table



(c) Circuit

Figure 6.98. FSM for parity generation.