

$$1.3) (a) \Gamma_o = \frac{Z_L - Z_o}{Z_L + Z_o} = \frac{(100 + j100) - 50}{(100 + j100) + 50} = 0.62 \angle 29.7^\circ$$

$$Z_{IN}(\frac{\lambda}{8}) = 50 \frac{(100 + j100) \cos 45^\circ + j50 \sin 45^\circ}{50 \cos 45^\circ + j(100 + j100) \sin 45^\circ} = 40 - j70 \Omega$$

$$V.S.W.R = \frac{1 + |\Gamma_o|}{1 - |\Gamma_o|} = \frac{1 + 0.62}{1 - 0.62} = 4.26$$

(b)

$$V(\frac{\lambda}{8}) = \frac{10 \angle 0^\circ (40 - j70)}{40 - j70 + 100} = 5.15 \angle -33.7^\circ$$

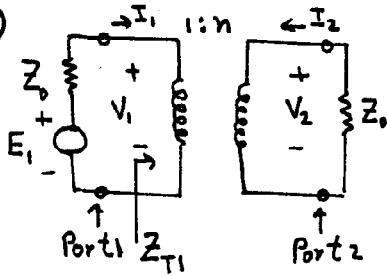
$$I(\frac{\lambda}{8}) = \frac{V(\frac{\lambda}{8})}{Z_{IN}(\frac{\lambda}{8})} = 0.064 \angle 26.6^\circ$$

$$P(\frac{\lambda}{8}) = \frac{1}{2} \text{Re}[V(\frac{\lambda}{8}) I^*(\frac{\lambda}{8})] = 82 \text{ mW}$$

$$V(\frac{\lambda}{8}) = 5.15 \angle -33.7^\circ = A_1 e^{j\frac{\pi}{4}} [1 + 0.62 \angle 29.7^\circ e^{-j\frac{\pi}{4}}]$$

$$\therefore A_1 = 3.643 \angle -56.31^\circ$$

1.11)



IN THE Z_o SYSTEM SHOWN, THE PARAMETERS S_{11} AND S_{21} ARE CALCULATED AS FOLLOWS:

$$I_2 = \frac{I_1}{n}, \quad V_2 = V_1 n$$

$$Z_{T1} = \frac{V_1}{I_1} = \frac{V_2}{I_2 n^2} = \frac{Z_o}{n^2}$$

$$S_{11} = \left. \frac{b_1}{a_1} \right|_{a_2=0} = \frac{Z_{T1} - Z_o}{Z_{T1} + Z_o} = \frac{\frac{Z_o}{n^2} - Z_o}{\frac{Z_o}{n^2} + Z_o} = \frac{1 - n^2}{1 + n^2}$$

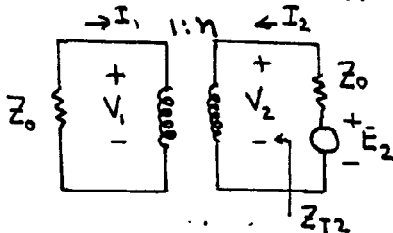
$$S_{21} = 2 \sqrt{\frac{Z_{o2}}{Z_{o1}}} \frac{V_2}{E_1} = 2 \frac{V_2}{E_1} \quad (1)$$

$$V_1 = \frac{E_1 Z_{T1}}{Z_{T1} + Z_o} = \frac{E_1 \frac{Z_o}{n^2}}{\frac{Z_o}{n^2} + Z_o} = \frac{E_1}{n^2 + 1}$$

$$V_2 = n V_1 = \frac{n E_1}{n^2 + 1} \quad \text{OR} \quad \frac{V_2}{E_1} = \frac{n}{n^2 + 1} \quad (2)$$

(2) INTO (1):

$$S_{21} = \frac{2n}{n^2 + 1}$$



THE PARAMETERS S_{22} AND S_{12} ARE CALCULATED AS FOLLOWS:

$$Z_{T2} = Z_o n^2$$

$$S_{22} = \left. \frac{b_2}{a_2} \right|_{a_1=0} = \frac{Z_{T2} - Z_0}{Z_{T2} + Z_0} = \frac{n^2 Z_0 - Z_0}{n^2 Z_0 + Z_0} = \frac{n^2 - 1}{n^2 + 1}$$

$$S_{12} = 2 \frac{V_1}{E_2} \quad (3)$$

$$V_2 = \frac{E_2 Z_{T2}}{Z_{T2} + Z_0} = \frac{E_2 Z_0 n^2}{Z_0 n^2 + Z_0} = \frac{E_2 n^2}{n^2 + 1}$$

$$V_1 = \frac{V_2}{n} = \frac{E_2 n}{n^2 + 1} \quad \text{OR} \quad \frac{V_1}{E_2} = \frac{n}{n^2 + 1} \quad (4)$$

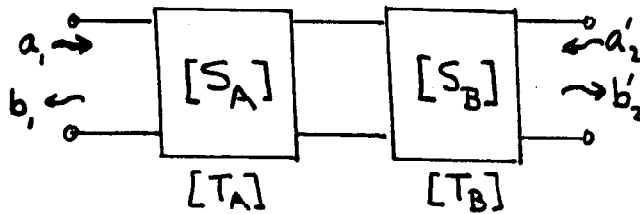
(4) INTO (3):

$$S_{12} = \frac{2n}{n^2 + 1}$$

AT PORTS 1' AND 2', WITH $\theta = \theta_1 = \theta_2$, WE OBTAIN:

$$[S'] = \begin{bmatrix} s_{11} e^{-j2\theta} & s_{12} e^{-j2\theta} \\ s_{21} e^{-j2\theta} & s_{22} e^{-j2\theta} \end{bmatrix} = e^{-j2\theta} \begin{bmatrix} \frac{1-n^2}{1+n^2} & \frac{2n}{n^2+1} \\ \frac{2n}{n^2+1} & \frac{n^2-1}{n^2+1} \end{bmatrix}$$

1.12)



[T] AND [S]
PARAMETERS ARE
RELATED BY (1.4.11)

FROM (1.4.13):

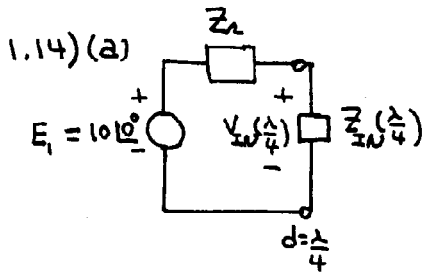
$$\begin{bmatrix} a_1 \\ b_1 \end{bmatrix} = \begin{bmatrix} T_{11}^A & T_{12}^A \\ T_{21}^A & T_{22}^A \end{bmatrix} \begin{bmatrix} T_{11}^B & T_{12}^B \\ T_{21}^B & T_{22}^B \end{bmatrix} \begin{bmatrix} b'_2 \\ a'_2 \end{bmatrix}$$

OVERALL T_{11} IS:

$$T_{11} = T_{11}^A T_{11}^B + T_{12}^A T_{21}^B$$

$$T_{11} = \frac{1}{S_{21}^A} \frac{1}{S_{21}^B} + \left(-\frac{S_{22}^A}{S_{21}^A} \right) \left(\frac{S_{11}^B}{S_{21}^B} \right)$$

$$\text{SINCE } T_{11} = \frac{1}{S_{21}} = \frac{1 - S_{22}^A S_{11}^B}{S_{21}^A S_{21}^B} \Rightarrow S_{21} = \frac{S_{21}^A S_{21}^B}{1 - S_{22}^A S_{11}^B}$$



$$Z_{IN}(\frac{\Delta}{4}) = \frac{Z_o^2}{Z_L} = \frac{50^2}{50 + j50} = 25 - j25$$

NOTE: If Z_L is given, THE VALUE OF Z_{IN} FOR MAXIMUM POWER IS $Z_{IN} = Z_L^*$. HOWEVER, IN THIS PROBLEM Z_{IN} IS GIVEN. HENCE, THE VALUE OF Z_L FOR MAX. POWER DELIVERED TO Z_{IN} IS: $Z_L = -\text{Im}[Z_{IN}]$

$$\therefore Z_L = j25$$

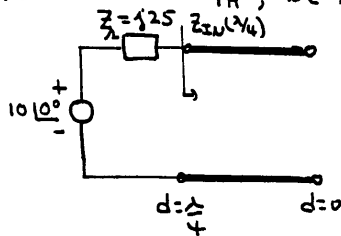
$$V_{IN}(\frac{\Delta}{4}) = \frac{10\angle 0^\circ (25 - j25)}{j25 + (25 - j25)} = 10 - j10 = 14.14 \angle -45^\circ$$

$$I_{IN}(\frac{\Delta}{4}) = \frac{14.14 \angle -45^\circ}{25 - j25} = 0.4$$

$$P_{IN} = \frac{1}{2} \text{Re}[14.14 \angle -45^\circ (0.4)] = 2 \text{ W}$$

$$P_L = P_{IN} = 2 \text{ W}$$

(b) TO FIND E_{TH} , WE FIND THE OPEN CIRCUIT VOLTAGE AT $d=0$



$$\Gamma_o = 1, V(d) = 2A \cos \beta d$$

$$I(d) = j2 \frac{A}{Z_o} \sin \beta d \quad (1)$$

$$Z_{IN}(\frac{\Delta}{4}) = 0 \text{ (A SHORT CIRCUIT)}$$

$$\therefore I(\frac{\Delta}{4}) = \frac{10\angle 0^\circ}{j25 + 0} = -j0.4 \quad (2)$$

$$\text{FROM (1) AND (2): } -j0.4 = j2 \frac{A}{50} \sin \frac{\pi}{2} \Rightarrow A = -10$$

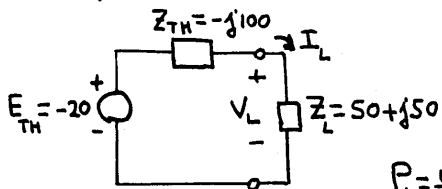
$$\text{HENCE: } V(d) = 2(-10) \cos \beta d = -20 \cos \beta d$$

$$E_{TH} = V(0) = -20$$

TO FIND Z_{TH} WE SET $E_1 = 0$, THEN:

$$Z_{TH} = \frac{Z_o^2}{Z_L} = \frac{50^2}{j25} = -j100$$

THE THEVENIN'S EQUIVALENT CIRCUIT AT $d=0$ IS:



$$I_L = \frac{-20}{-j100 + 50 + j50} = 0.283 \angle -135^\circ$$

$$V_L = 0.283 \angle -135^\circ (50 + j50) = 20 \angle -90^\circ$$

$$P_L = \frac{1}{2} \text{Re}[20 \angle -90^\circ (0.283 \angle 135^\circ)] = 2 \text{ W}$$

$$1.16) (a) Z_{IN}(0) = Z_{IN}(d) \Big|_{d=\frac{\lambda}{8}} = 50 \frac{(150 + j150) + j50 \tan 45^\circ}{50 + j(150 + j150) \tan 45^\circ} = 23 - j65 \Omega$$

$$(b) a_1(0) = \frac{1}{2\sqrt{Z_0}} [V_1(0) + Z_0 I_1(0)] \quad , \quad V_1(0) = E_1 - Z_0 I_1(0)$$

$$\therefore a_1(0) = \frac{E_1}{2\sqrt{Z_0}} = \frac{10}{2\sqrt{50}} = 0.707$$

$$a_1\left(\frac{\lambda}{8}\right) = a_1(0) e^{-j\pi/4} = 0.707 \angle -45^\circ$$

$$b_1(0) = \frac{1}{2\sqrt{50}} [V_1(0) - 50 I_1(0)] = \frac{1}{2\sqrt{50}} [10 - 50 I_1(0) - 50 I_1(0)] \quad (1)$$

$$I_1(0) = \frac{10 \angle 0^\circ}{50 + 23 - j65} = 0.102 \angle 41.68^\circ \quad (2)$$

$$(2) \text{ INTO } (1): \quad b_1(0) = \frac{1}{2\sqrt{50}} [10 - 2(50)(0.102 \angle 41.68^\circ)] = 0.508 \angle -70.65^\circ$$

$$b_1\left(\frac{\lambda}{8}\right) = b_1(0) e^{j\pi/4} = 0.508 \angle -25.65^\circ$$

SINCE $Z_2 = Z_0$, THE OUTPUT IS MATCHED. HENCE, $a_2(0) = 0$

$$(c) V_1(0) = I_1(0) Z_{IN}(0) = 0.102 \angle 41.68^\circ (23 - j65) = 7.05 \angle -28.8^\circ$$

$$\text{OR } V_1(0) = \sqrt{Z_0} [a_1(0) + b_1(0)] = \sqrt{50} [0.707 + 0.508 \angle -70.65^\circ] = 7.05 \angle -28.8^\circ$$

$$V_1\left(\frac{\lambda}{8}\right) = \sqrt{Z_0} [a_1\left(\frac{\lambda}{8}\right) + b_1\left(\frac{\lambda}{8}\right)] = \sqrt{50} [0.707 \angle -45^\circ + 0.508 \angle -25.65^\circ] = 8.47 \angle -36.92^\circ$$

$$I_1\left(\frac{\lambda}{8}\right) = \frac{8.47 \angle -36.92^\circ}{150 + j150} = 0.04 \angle -81.92^\circ$$

$$(d), (e) P_1(0) = \frac{1}{2} \text{Re}[V_1(0) I_1^*(0)] = 0.12 \text{ W} \quad , \quad P_1\left(\frac{\lambda}{8}\right) = \frac{1}{2} \text{Re}[V_1\left(\frac{\lambda}{8}\right) I_1^*\left(\frac{\lambda}{8}\right)] = 0.12 \text{ W}$$

$$\text{Also: } P_1(0) = P_1\left(\frac{\lambda}{8}\right) = \frac{1}{2} |a_1(0)|^2 - \frac{1}{2} |b_1(0)|^2 = \frac{1}{2} |a_1\left(\frac{\lambda}{8}\right)|^2 - \frac{1}{2} |b_1\left(\frac{\lambda}{8}\right)|^2 = \frac{1}{2} (0.707)^2 - \frac{1}{2} (0.508)^2 = 0.12 \text{ W}$$

$$(f) S_{11}\left(\frac{\lambda}{8}\right) = \frac{Z_{T1} - Z_0}{Z_{T1} + Z_0} = \frac{150 + j150 - 50}{150 + j150 + 50} = 0.721 \angle 19.44^\circ$$

$$S_{11}(0) = S_{11}\left(\frac{\lambda}{8}\right) e^{-j2(\pi/4)} = 0.721 \angle 19.44^\circ (\angle -90^\circ) = 0.721 \angle -70.56^\circ$$

$$(g) (VSWR)_{in} = \frac{1 + |S_{11}|}{1 - |S_{11}|} = 6.17 \quad , \quad (VSWR)_{out} = 1$$

$$(h) \lambda = \frac{3 \times 10^8}{10^9} = 0.3 \text{ m (OR } 30 \text{ cm)} \quad . \quad \ell = \frac{\lambda}{8} = \frac{30}{8} = 3.75 \text{ cm}$$

$$(i) b_2\left(\frac{\lambda}{8}\right) = S_{21} a_1\left(\frac{\lambda}{8}\right) + S_{22} a_2\left(\frac{\lambda}{8}\right) = 3 \angle 60^\circ (0.707 \angle -45^\circ) = 2.12 \angle 15^\circ$$

$$P_2(0) = \frac{1}{2} |b_2(0)|^2 = \frac{1}{2} |b_2\left(\frac{\lambda}{8}\right)|^2 = \frac{1}{2} (2.12)^2 = 2.25 \text{ W}$$

$$1.17) (a) \left. Z_{IN}(0) = Z_{IN}(d) \right|_{d=\frac{\lambda}{4}} = 75 \frac{(150 + j150) + j75 \tan 45^\circ}{75 + j(150 + j150) \tan 45^\circ} = 60 - j105 \Omega$$

(b) THE VSWR IN THE $\lambda_2 = \frac{\lambda}{4}$ LINE IS UNITY, SINCE THE LINE IS MATCHED.

$$\text{IN THE } \lambda_1 = \frac{\lambda}{8} \text{ LINE: } \Gamma_0 = \frac{(150 + j150) - 75}{(150 + j150) + 75} = 0.62 \angle 29.7^\circ$$

$$\therefore \text{VSWR} = \frac{1 + 0.62}{1 - 0.62} = 4.26$$

$$(c) V_1(0) = \frac{10 \angle 0^\circ Z_{IN}(0)}{Z_{IN}(0) + Z_1} = \frac{10(60 - j105)}{60 - j105 + 100} = 6.32 \angle -26.98^\circ$$

$$I_1(0) = \frac{V_1(0)}{Z_{IN}(0)} = \frac{6.32 \angle -26.98^\circ}{60 - j105} = 0.0523 \angle 33.27^\circ$$

$$a_1(0) = \frac{1}{2\sqrt{75}} [V_1(0) + 75 I_1(0)] = 0.516 \angle -4.6^\circ$$

$$b_1(0) = \frac{1}{2\sqrt{75}} [V_1(0) - 75 I_1(0)] = 0.32 \angle -64.88^\circ$$

$$a_1\left(\frac{\lambda}{8}\right) = a_1(0) e^{-j\pi/4} = 0.516 \angle -49.6^\circ$$

$$b_1\left(\frac{\lambda}{8}\right) = b_1(0) e^{j\pi/4} = 0.32 \angle -19.8^\circ$$

$$a_2(0) = 0$$

$$(d) P_1(0) = \frac{1}{2} |a_1(0)|^2 - \frac{1}{2} |b_1(0)|^2 = \frac{1}{2} (0.516)^2 - \frac{1}{2} (0.32)^2 = 0.082 \text{ W}$$

$$P_1\left(\frac{\lambda}{8}\right) = \frac{1}{2} |a_1\left(\frac{\lambda}{8}\right)|^2 - \frac{1}{2} |b_1\left(\frac{\lambda}{8}\right)|^2 = \frac{1}{2} (0.516)^2 - \frac{1}{2} (0.32)^2 = 0.082 \text{ W}$$

$$(e) P_{AVS} = \frac{|E_1|^2}{8 \operatorname{Re}[Z_1]} = \frac{(10)^2}{8(100)} = 0.125 \text{ W}$$

$$\frac{1}{2} |a_1(0)|^2 = 0.133 \text{ W}$$

SINCE $Z_1 \neq Z_0$, IT FOLLOWS THAT $P_{AVS} \neq \frac{1}{2} |a_1(0)|^2$

1.19) IN EXAMPLE 1.71: $V = 5.59 \angle -26.57^\circ$, $a_p = 0.5$, $b_p = 0$

$$(a) V_p^+ = \frac{E_n Z_n^*}{2R_n} = \frac{10(100 - j50)}{2(100)} = 5.59 \angle -26.57^\circ$$

$$V_p^- = V - V_p^+ = 5.59 \angle -26.57^\circ - 5.59 \angle -26.57^\circ = 0$$

$$(b) a_p = \frac{\sqrt{R_n}}{Z_n^*} V_p^+ = \frac{\sqrt{100}}{100 - j50} (5.59 \angle -26.57^\circ) = 0.5$$

$$b_p = \frac{\sqrt{R_n}}{Z_n} V_p^- = 0$$

1.25)(a) FOR REAL $[Z_0]$ AND $[Y_0]$

$$[I] = [y][V]$$

$$[I^-] = [I^+] - [I]$$

$$[V^-][Y_0] = [V^+][Y_0] - [y]([V^+] + [V^-])$$

$$([Y_0] + [y])[V^-] = ([Y_0] - [y])[V^+]$$

$$[V^-] = ([Y_0] + [y])^{-1} ([Y_0] - [y])[V^+]$$

$$= [S][V^+]$$

$$\therefore [S] = -([Y_0] + [y])^{-1} ([y] - [Y_0]) \quad (1)$$

$$\begin{aligned}
[Y_0] - [y] &= [Y_0][S] + [y][S] \\
[Y_0]([I] - [S]) &= [y]([I] + [S]) \\
[y] &= [Y_0]([I] - [S])([I] + [S])^{-1}
\end{aligned}$$

(b) FROM (1):

$$[S] = - \left[\begin{bmatrix} Y_0 & 0 \\ 0 & Y_0 \end{bmatrix} + \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \right]^{-1} \left[\begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} - \begin{bmatrix} Y_0 & 0 \\ 0 & Y_0 \end{bmatrix} \right]$$

$$[S] = - \begin{bmatrix} y_{11} + Y_0 & y_{12} \\ y_{21} & y_{22} + Y_0 \end{bmatrix}^{-1} \begin{bmatrix} y_{11} - Y_0 & y_{12} \\ y_{21} & y_{22} - Y_0 \end{bmatrix}$$

$$\begin{bmatrix} y_{11} + Y_0 & y_{12} \\ y_{21} & y_{22} + Y_0 \end{bmatrix}^{-1} = \frac{\begin{bmatrix} y_{22} + Y_0 & -y_{12} \\ -y_{21} & y_{11} + Y_0 \end{bmatrix}}{(y_{11} + Y_0)(y_{22} + Y_0) - y_{12}y_{21}}$$

$$\therefore [S] = - \frac{\begin{bmatrix} (y_{22} + Y_0)(y_{11} - Y_0) - y_{12}y_{21} & (y_{22} + Y_0)y_{12} - y_{12}(y_{22} - Y_0) \\ -y_{21}(y_{11} - Y_0) + y_{21}(y_{11} + Y_0) & -y_{12}y_{21} + (y_{11} + Y_0)(y_{22} - Y_0) \end{bmatrix}}{(y_{11} + Y_0)(y_{22} + Y_0) - y_{12}y_{21}}$$

$$[S] = \frac{1}{\Delta_2} \begin{bmatrix} (1 - y'_{11})(1 + y'_{22}) + y'_{12}y'_{21} & -2y'_{12} \\ -2y'_{21} & (1 + y'_{11})(1 - y'_{22}) + y'_{12}y'_{21} \end{bmatrix}$$

WHERE $\Delta_2 = (1 + y'_{11})(1 + y'_{22}) - y'_{12}y'_{21}$, $y'_{11} = y_{11}Z_0$, $y'_{12} = y_{12}Z_0$,
 $y'_{21} = y_{21}Z_0$, AND $y'_{22} = y_{22}Z_0$ ($Y_0 = 1/Z_0$).