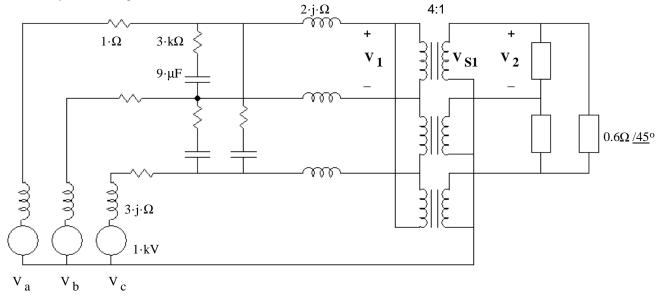
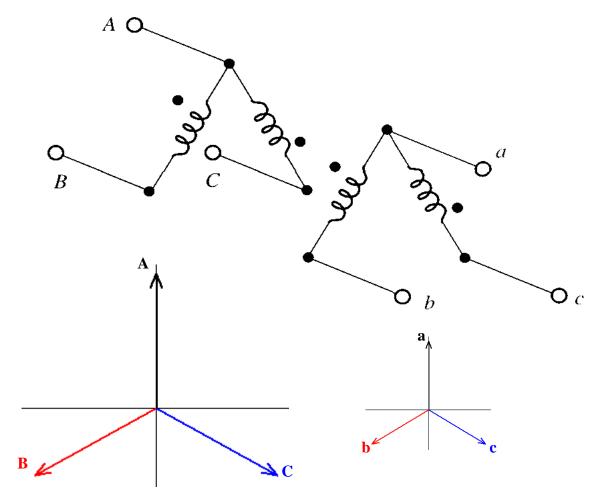
4. a) Draw a per-phase drawing of for the balanced 3-phase, 60-Hz system shown. You may neglect phase issues introduced by Y- Δ and Δ -Y connections. You may need to modify the turns ratio of the transformer to reflect Y- Δ and Δ -Y connections. Be sure to show values of the source, passive components and turns ratio on your drawing.



b) Find $\frac{V_1}{V_2}$ inclding phase angle

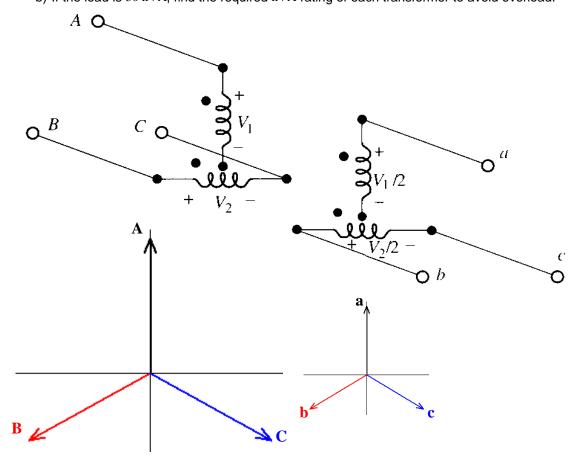
Modify turns ratio to reflect Δ -Y transformer connection

- 5. The configuration shown is called the "open-delta" or "V" connection, for obvious reasons. Identical 2:1 transformers are used.
 - a) Show that if ABC is 480-V balanced three phase, abc is 240-V balanced three-phase. Consider the ABC voltages to be a three-phase set and prove the abc set is three-phase.



b) If the load is $30\,\mathrm{kVA}$, find the required kVA rating of the transformers to avoid overload. [You can solve this independent of part a)]

6. The configuration shown is called the "T" connection. For this connection, the 2:1 transformers are not identical but have different voltage and kVA ratings. The bottom transformer is center-tapped so as to have equal, in-phase voltages for each half.b) If the load is 30 kVA, find the required kVA rating of each transformer to avoid overload.



7. A phase-shifting transformer has a complex turns ratio of $\mathbf{t} := 4 \cdot e^{\mathbf{j} \cdot 20 \cdot \text{deg}} = 4 \cdot \frac{200}{200}$

It has a series impedance of $\mathbf{Z}_{\mathbf{S}} := (0.05 + j \cdot 0.6) \cdot \Omega$ Find the admittance matrix of this tranformer (see the last page of the transformer notes).

$$\mathbf{Y}_{\mathbf{S}} := \frac{1}{\mathbf{Z}_{\mathbf{S}}} =$$

$$\begin{bmatrix} \mathbf{Y}_{\mathbf{S}} & -\frac{\mathbf{Y}_{\mathbf{S}}}{\mathbf{t}} \\ -\frac{\mathbf{Y}_{\mathbf{S}}}{\bar{\mathbf{t}}} & \frac{\mathbf{Y}_{\mathbf{S}}}{(|\mathbf{t}|)^2} \end{bmatrix} = \begin{bmatrix} \mathbf{Y}_{\mathbf{S}} & \mathbf{Y}_{\mathbf{S}} \\ -\mathbf{Y}_{\mathbf{S}} & \mathbf{Y}_{\mathbf{S}} \\ -\mathbf{Y}_{\mathbf{S}} & \mathbf{Y}_{\mathbf{S}} \end{bmatrix}$$