

Name: _____

Homework # Bd4

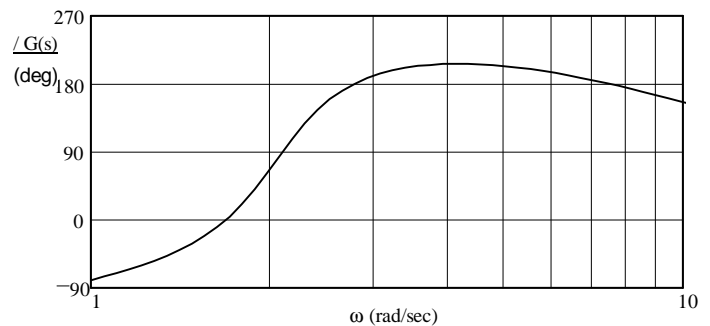
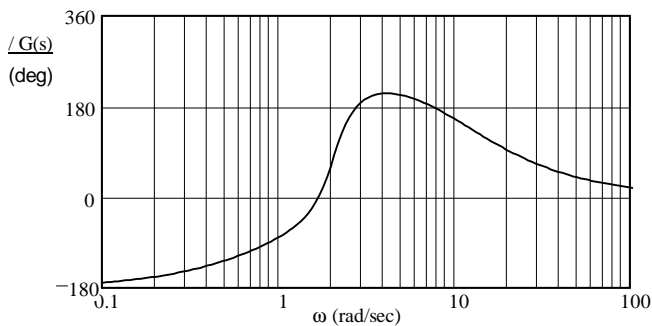
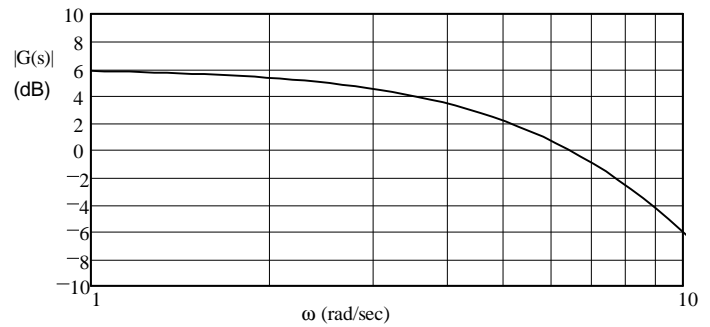
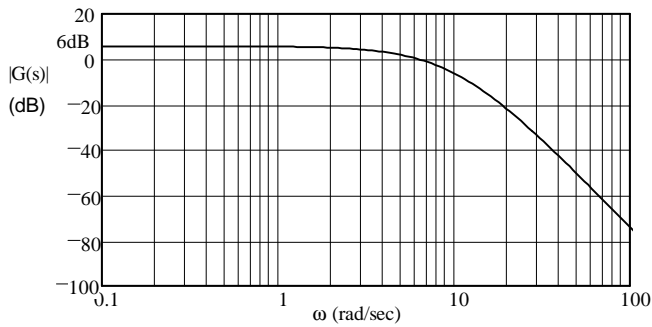
a

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1. Problem 5.13 b & new c & d (p.149) in the text.

b) Bode plots of the open-loop transfer function of a feedback system are shown below, with the detail from 1 to 10 rad/sec shown on the left. For this system:

- How much can the open-loop gain be changed (increased and/or decreased) before the closed-loop system becomes unstable ?
- What is a rough estimate of the phase margin of the feedback system? Show on the graph how the results are obtained. The numerical results do not have to be precise.
- How much time delay can there be in feedback system before the phase margin disappears.



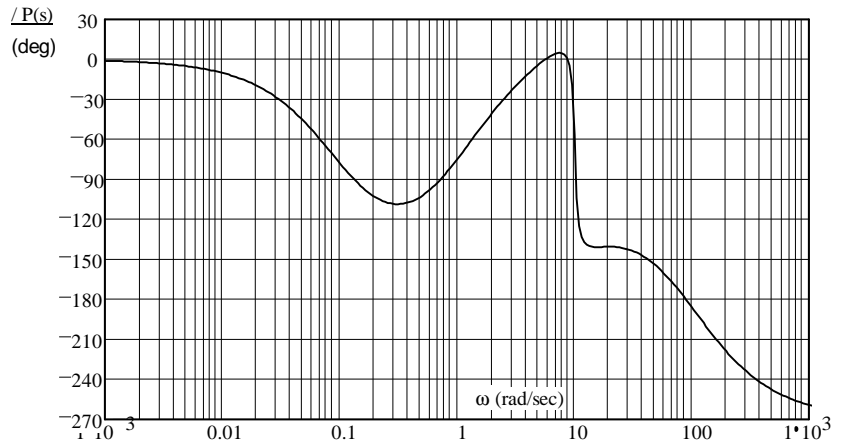
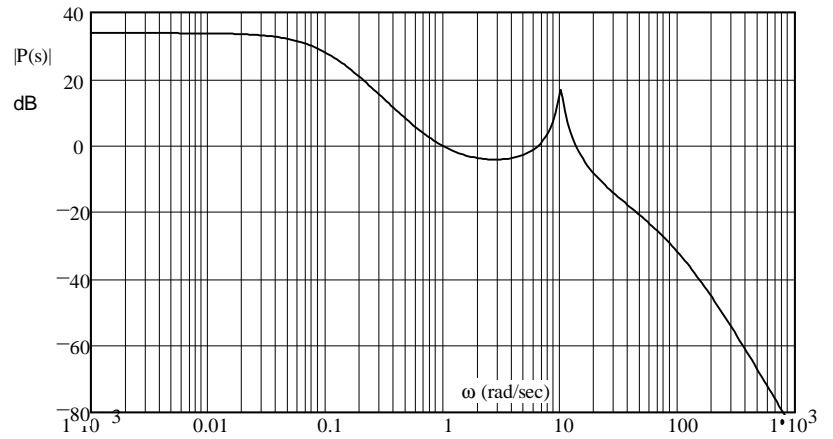
c) For the system of part (a), give the steady-state response of the open-loop system an input $x(t) = 4\cos(10t)$. express the answer in the time-domain.

d) Give the steady-state response of the closed-loop system for the same input. Hint: closed loop output is: $\text{input} \cdot \frac{G(10 \cdot j)}{1 + G(10 \cdot j)}$

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2. Like problem 5.9a (p.147) in the Bodson text.

- a) Give the gain margin, the phase margin and the delay margin of the system whose Bode plots are shown at right (the plots are for the open-loop transfer function and the closed-loop transfer function is assumed to be stable).



Add another sheet of paper the following:

3. A system has a delay of $D := 0.01$ -sec. How many degrees of phase does this represent at:

- a) $f := 1$ -Hz $f := 10$ -Hz $f := 100$ -Hz $f := 1$ -kHz
 b) $\omega := 1 \cdot \frac{\text{rad}}{\text{sec}}$ $\omega := 10 \cdot \frac{\text{rad}}{\text{sec}}$ $\omega := 100 \cdot \frac{\text{rad}}{\text{sec}}$ $\omega := 1000 \cdot \frac{\text{rad}}{\text{sec}}$

4. a) If the phase response of a pure time delay were plotted on linear phase vs. linear frequency plot, what would be the shape of the curve?
 b) If the phase response of a pure time delay were plotted on linear phase vs. logarithmic frequency plot, what would be the shape of the curve?

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Answers

1. b) Gain may be increased by ≈ 2 dB and reduced by ≈ 4.4 dB. PM ≈ 13 -deg DM ≈ 36 -ms
 c) $2 \cdot \cos(10 \cdot t + 158 \cdot \text{deg})$ d) $3.5 \cdot \cos(10 \cdot t + 140 \cdot \text{deg})$
2. a) GM ≈ 30 -dB PM ≈ 40 -deg DM ≈ 50 -ms
3. a) 3.6-deg 36-deg 360-deg 3600-deg b) 0.573-deg 5.73-deg 57.3-deg 573-deg
4. a) A straight line of negative slope, ωD , where D is the time delay.
 b) A negative sloping line with a slope of ωD . Since the frequency increases by a factor of 10 each decade, so would the downward slope of the line.