Exam 3 Study Guide AND Homework M1

The exam will be **closed book**, but you may use the colored sheets from exam 1 and 2 the new one for exam 3. **Download old exams from HW page on class web site.**

The exam will cover

1. Root - Locus method

a) Main rules (memorize, could be in closed-book part)

b) Gain at any point on the root locus: $k = \frac{1}{|G(s)|}$ (both parts)

c) Additional rules.

The **breakaway/in points** are also solutions to:

Phase angle of G(s) at any point on the root locus: Or: $\arg\left(\frac{1}{2}\right) = \arg(D(s)) - \arg(D(s)) = \pm 180^{\circ}, \pm 540^{\circ}, \dots$

$$\left| \frac{\operatorname{deg}}{\operatorname{G}(s)} \right| = \operatorname{deg}(\operatorname{D}(s)) = \operatorname{deg}(\operatorname{H}(s)) = \underline{+} \operatorname{Hoo}(s, \underline{+})$$

Departure angles from complex poles: Example. 180 - 90 - 153.4 + 135 = 71.6 deg

2. Root - Locus Interpretation and design

Concepts of what a root locus plot is and what it tells you. Movement of poles Good vs bad, fast response vs slow, OK damping vs bad. Compensators

Know pole & zero locations of P, PI, lag, PD, lead & PID Compensators.

PI and Lag, purpose and design, ties in with steady-state error

PD and Lead, purpose and design ties in with root locus angle rules

Choose points on the s-plane to achieve given required characteristics based on the 2nd-order assumption (RL Crib) Know that the 2nd-order assumption may be accurate if other CL poles and/or zeros aren't 5x farther from Imag. axis.

Design of a compensator to force the RL point through a given point (like RL7).

3. Unconventional root-locus

4. Phase-locked loops Material from labs How a How does it work The lo

How and why did you use an unconventional root-locus The loop block diagram

- 5. Compensator circuits & Instrumentation amplifier
- 6. PID tuning, memorize some basic ideas, like why you would need to do it.
- 7. PLCs and Ladder logic. AND, OR, XOR & basic switching logic could be asked in the closed-book part.
- 8. Bode Plots (limited to page 1 of notes)

Be able to draw both magnitude and phase plots

Be able to draw the smoth curves as well as the the asymptotic lines

I may ask you to start with a circuit

Basic rules

9. Concentrate on Homeworks RL5 - Bd1 I'll scan through for problems

10. Up to Lab 7 (Advanced PLL)

ECE 3510 homework # M1 Requires action on Thur, 4/18 Due Mon, 4/22

Go to ME Design day in the Union on Thursday, 4/18 sometime from 11:00 to 3:00. See www.mech.utah.edu/events/designday.html Write **several paragraphs** about what you see there. Especially:

- 1. Note control systems and/or systems with feedback.
- 2. Tell which senior project most impressed you and why.
- 3. Observe at least part of one of the competitions (main mechatronics robot competition, 1:00 3:00) and write at least one paragraph about it (suggest improvements).

-3 -2 -1 -1j



 $\sum_{all} \frac{1}{\left(s + p_{i}\right)} = \sum_{all} \frac{1}{\left(s + z_{i}\right)}$

Exam 3 is Mon, 4/8/19