## Exam 3 Study Guide Exam 3 is Thur, 4/5/07

1. Root Locus

Concepts of what a root locus plot is and what it tells you. Movement of poles

Be able to determine which closed-loop poles will dominate the response.

relative coefficient =  $\frac{\Sigma \text{ distance to CL zeros}}{\Sigma \text{ distance to OL poles}}$ 

Consider both complex poles together as one

Good vs bad, fast response vs slow, OK damping vs bad.

Effects of adding a compensator

Know pole & zero locations of P, PD, PI, & PID Compensators as well as Lag and Lead Conclusions, see section 4.4.5, p.82

2. Phase-locked loops

How does it work

The loop block diagram

Material from labs

3. Bode Plots

Be able to draw both magnitude and phase plots

I may ask you to start with a circuit

Basic rules

Complex poles an zeros

$$(s+a)^{2} + b^{2} = s^{2} + 2 \cdot a \cdot s + a^{2} + b^{2}$$
$$= s^{2} + 2 \cdot \zeta \cdot \omega_{n} \cdot s + \omega_{n}^{2} \qquad \text{max at} \quad \omega_{n} \quad , \quad \frac{1}{2 \cdot \zeta}$$

Bode to transfer function (like problem 5.2b)

GM, PM & DM

4. Nyquist plots

You may be asked to draw one

Be able to the start point (DC gain ( $s = 0 = \omega$ )) from the transfer function)

Find the final value (  $\omega = \infty$  ) and the approach angle to the final value.

Be able to deal with poles at zero.

Concepts of what a Nyquist plot is and what it tells you. Z = N + P Make sure you understand problem 5.11 Be able to count encirclements, with or without the  $\omega < 0$  part of the plot.

GM, PM & DM

- 5. Phase-lead compensator (p.133)
- 6. HW 11 19
- 7. Labs 5 8