ECE 3510 Exam 1 Study Guide

First Exam will be on Friday 2/10/17

The exam will be closed book, with calculator, but will include the information shown below, if needed.

The exam will cover

Information you will be given (closed book part, if needed)

 $F(s) = \int_{0}^{\infty} f(t) \cdot e^{-s \cdot t} dt$

Laplace Transform table class handout

Standard feedback loop transfer function

B(s)

A(s)

Euler's equations

- 1. Signals and blocks in a feedback loop
- 2. Laplace transforms

You may have to find a simple Laplace transform from the basic relation.

You may have to look up and adapt a table entries

- 3. Inverse Laplace transforms (partial fractions)
- 4. Relationship of signals to pole locations
- 5. Boundedness and convergence of signals
- 6. H(s) of circuits
- 7. Block Diagrams & their transfer functions Including general interconnected systems
- 8. BIBO Stability
- 9. Impulse & step responses
- 10. Steady-state (DC gain) & transient step responses
- 11. Effects of pole locations on step response
- 12. Sinusoidal responses, effects of poles & zeros, etc.

Steady-state AC analysis to get $y_{ss}(t)$

- 13. Transient response to sinusoidal inputs

$$\mathbf{Y}(s) = \frac{b_{2} \cdot s^{2} + b_{1} \cdot s + b_{0}}{s^{2} + a_{1} \cdot s + a_{0}} \cdot \mathbf{X}(s)$$

14. Effect of initial conditions
$$\mathbf{Y}(s) = \frac{\mathbf{b} \ 2^{\cdot s^2 + \ b} \ 1^{\cdot s + \ b} \ 0}{s^2 + a \ 1^{\cdot s + \ a} \ 0} \cdot \mathbf{X}(s) + \frac{s \cdot y(0) + \frac{d}{dt} y(0) + a \ 1^{\cdot y}(0) - b \ 2^{\cdot s} \cdot x(0) - b \ 2^{\cdot \frac{d}{dt}} x(0) - b \ 1^{\cdot x}(0)}{s^2 + a \ 1^{\cdot s + \ a} \ 0}$$

15. Know the advantages of the state-space method

Easily handles multiple inputs, multiple outputs and initial conditions

Can be used with nonlinear systems

Can be used with time-varying systems

Reveals unstable systems that have stable transfer functions (pole-zero cancellations). You can determine:

Controllability: State variables can all be affected by the input

Observability: State variables are all "observeable" from the output

Basis of Optimal and Adaptive control methods

- 16. Homeworks 1 7
- 17. Labs 1 & 2

You can download old exams from Homework and Notes page on class web site.

But remember, they may cover more than we did in our class.

http://www.ece.utah.edu/~ece3510/