

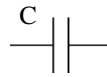
Laplace impedances

Resistor



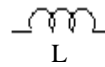
$Z_R = R$

Capacitor



$Z_C = \frac{1}{C \cdot s}$

Inductor



$Z_L = L \cdot s$

Transfer function

Use Laplace impedances, manipulate your circuit equation(s) to find a transfer function:

Rearrange circuit equation to: $H(s) = \frac{\text{output}}{\text{input}} = \frac{V_X(s)}{V_{in}(s)}$ = transfer function

May be I_X or any desired variable
 May be I_{in} or any forcing function
 a_1, b_1, k_1 coefficients may be zero

Characteristic equation

To find the poles of the transfer function

characteristic equation

$s^2 + b \cdot s + k = 0$

Complete solution

Solutions to the characteristic equation: $s_1 = -\frac{b}{2} + \frac{\sqrt{b^2 - 4 \cdot k}}{2}$ $s_2 = -\frac{b}{2} - \frac{\sqrt{b^2 - 4 \cdot k}}{2}$

Find initial Conditions (v_C and/or i_L)

Find conditions of just before time $t = 0$, $v_C(0^-)$ and $i_L(0^-)$. These will be the same just after time $t = 0$, $v_C(0^+)$ and $i_L(0^+)$ and will be your initial conditions.

Use normal circuit analysis to find your desired variable: $v_X(0)$ or $i_X(0)$

Also find: $\frac{d}{dt} v_X(0)$ or $\frac{d}{dt} i_X(0)$ The trick to finding these is to see that: $\frac{d}{dt} v_C(0) = \frac{i_C(0)}{C}$ and $\frac{d}{dt} i_L(0) = \frac{v_L(0)}{L}$

Find final conditions ("steady-state" or "forced" solution)

DC inputs: Inductors are shorts Capacitors are opens Solve by DC analysis $v_X(\infty)$ or $i_X(\infty)$

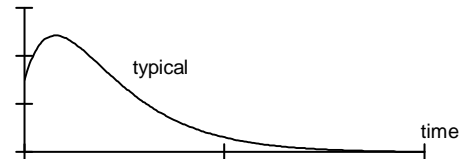
AC inputs: Solve by AC steady-state analysis using $j\omega$

$X(t)$ may be replaced by $v_X(t)$, $i_X(t)$ or any desired variable in the equations below

Overdamped $b^2 - 4 \cdot k > 0$ s_1 and s_2 are real and negative

$X(t) = X(\infty) + B \cdot e^{s_1 \cdot t} + D \cdot e^{s_2 \cdot t}$

$X(0) = X(\infty) + B + D$ $\frac{d}{dt} X(0) = B \cdot s_1 + D \cdot s_2$ Solve simultaneously for B and D.

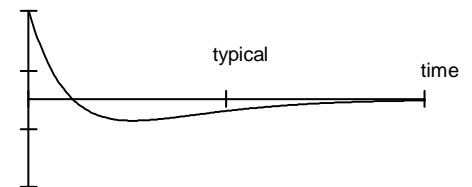


Critically damped $b^2 - 4 \cdot k = 0$ $s_1 = s_2 = -\frac{b}{2} = s$ s_1 and s_2 are real, equal and negative

$X(t) = X(\infty) + B \cdot e^{-s \cdot t} + D \cdot t \cdot e^{-s \cdot t}$

$X(0) = X(\infty) + B$

so.. $B = X(0) - X(\infty)$ $\frac{d}{dt} X(0) = B \cdot s + D$ so.. $D = \frac{d}{dt} X(0) - B \cdot s$

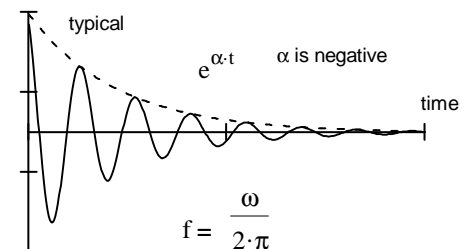


Underdamped $b^2 - 4 \cdot k < 0$ $s_1 = \alpha + j \cdot \omega$ $s_2 = \alpha - j \cdot \omega$ α is negative
 complex s_1 and s_2

$X(t) = X(\infty) + e^{\alpha \cdot t} \cdot (B \cdot \cos(\omega \cdot t) + D \cdot \sin(\omega \cdot t))$

$X(0) = X(\infty) + B$

so.. $B = X(0) - X(\infty)$ $\frac{d}{dt} X(0) = B \cdot \alpha + D \cdot \omega$ so.. $D = \frac{\frac{d}{dt} X(0) - B \cdot \alpha}{\omega}$



Derivation of the Canned Solutions, Second Order Transients

ECE 2210

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How do we find B and D ?? You will use the canned solutions, which I will derive here, using initial conditions.

These are worked out within an example, starting on page 1.12 of the main Second-Order Transients handout.

Overdamped

Let's assume we've found that s_1 and s_2 are real and negative, and you're interested in the capacitor voltage.

$$\text{Then: } v_C(t) = v_C(\infty) + B \cdot e^{s_1 t} + D \cdot e^{s_2 t}$$

At time $t=0$ $v_C(0) = v_C(\infty) + B + D = v_C(0^-)$, whatever it was just before time $t=0$. It CANNOT change instantly
Same for $i_L(0)$

But that's only one equation, and we have two unknowns, B and D.

The trick is to differentiate the solution: $v_C(t) = v_C(\infty) + B \cdot e^{s_1 t} + D \cdot e^{s_2 t}$

$$\frac{d}{dt} v_C(t) = 0 + B \cdot s_1 \cdot e^{s_1 t} + D \cdot s_2 \cdot e^{s_2 t}$$

$$\text{At time } t=0: \frac{d}{dt} v_C(0) = B \cdot s_1 + D \cdot s_2 = \text{initial slope}$$

$$\text{From initial conditions, above: } \frac{d}{dt} v_C(0) = \frac{i_C(0)}{C} = B \cdot s_1 + D \cdot s_2 \quad \text{The second equation !}$$

Solve simultaneously for B and D.

But i_C CAN change instantly, so...

We will find $i_C(0)$ from $i_L(0) = i_L(0^-)$ because i_L can't change instantly

This will require circuit analysis at time $t=0+$

Underdamped

Let's assume we've found complex s_1 and s_2 $s_1 = \alpha + j\omega$ $s_2 = \alpha - j\omega$ α is negative

$$\text{Then: } v_C(t) = v_C(\infty) + e^{\alpha t} \cdot (B \cdot \cos(\omega t) + D \cdot \sin(\omega t))$$

$$\text{At time } t=0 \quad v_C(0) = v_C(\infty) + B = v_C(0^-) \quad B = v_C(0) - v_C(\infty)$$

Now differentiate the solution: $v_C(t) = v_C(\infty) + e^{\alpha t} \cdot (B \cdot \cos(\omega t) + D \cdot \sin(\omega t))$

$$\text{recall: } \frac{d}{dt}(f(t) \cdot g(t)) = \left(\frac{d}{dt} f(t)\right) \cdot g(t) + f(t) \cdot \left(\frac{d}{dt} g(t)\right)$$

$$\text{yields: } \frac{d}{dt} v_C(t) = \alpha \cdot e^{\alpha t} \cdot (B \cdot \cos(\omega t) + D \cdot \sin(\omega t)) + e^{\alpha t} \cdot (-B \cdot \sin(\omega t) \cdot \omega + D \cdot \cos(\omega t) \cdot \omega)$$

$$\text{At time } t=0: \frac{d}{dt} v_C(0) = B \cdot \alpha + D \cdot \omega \quad \text{Solve for: } D = \frac{\frac{d}{dt} v_C(0) - B \cdot \alpha}{\omega}$$

Critically damped

Let's assume we've found real $s_1 = s_2 = s$

$$\text{Then: } v_C(t) = v_C(\infty) + B \cdot e^{s t} + D \cdot t \cdot e^{s t}$$

$$\text{At time } t=0 \quad v_C(0) = v_C(\infty) + B = v_C(0^-) \quad B = v_C(0) - v_C(\infty)$$

Now differentiate the solution: $\frac{d}{dt} v_C(t) = B \cdot s \cdot e^{s t} + D \cdot e^{s t} + D \cdot t \cdot s \cdot e^{s t}$

$$\frac{d}{dt} v_C(0) = B \cdot s + D \quad \text{Solve for: } D = \frac{d}{dt} v_C(0) - B \cdot s$$

Same goes for and variable (like $i_L(t)$, for example). $v_C(0+) = v_C(0-)$ $i_L(0+) = i_L(0-)$

$$\frac{d}{dt} v_C(0) = \frac{i_C(0)}{C} \quad \frac{d}{dt} i_L(0) = \frac{v_L(0)}{L}$$

And circuit analysis at time $t=0+$